



PERiLS PBL Profiling: *CLAMPS and CopterSonde UAS*

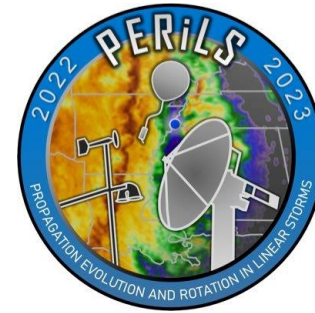
Dr. Elizabeth Smith Research Meteorologist–NOAA National Severe Storms Laboratory
Affiliated Assistant Professor–OU School of Meteorology



Tyler Bell, Joshua Gebauer, Tony Segales – OU CIWRO



Our Context: PERiLS



Similar goals – understand storms and environments, etc – and building on VORTEX-SE lessons while going *partly mobile* to target quasi-linear convection systems (QLCSs)

Southeast US complexity invites innovation to meet mission needs:

- Observation platforms
- Observation strategies
- Observation analysis products



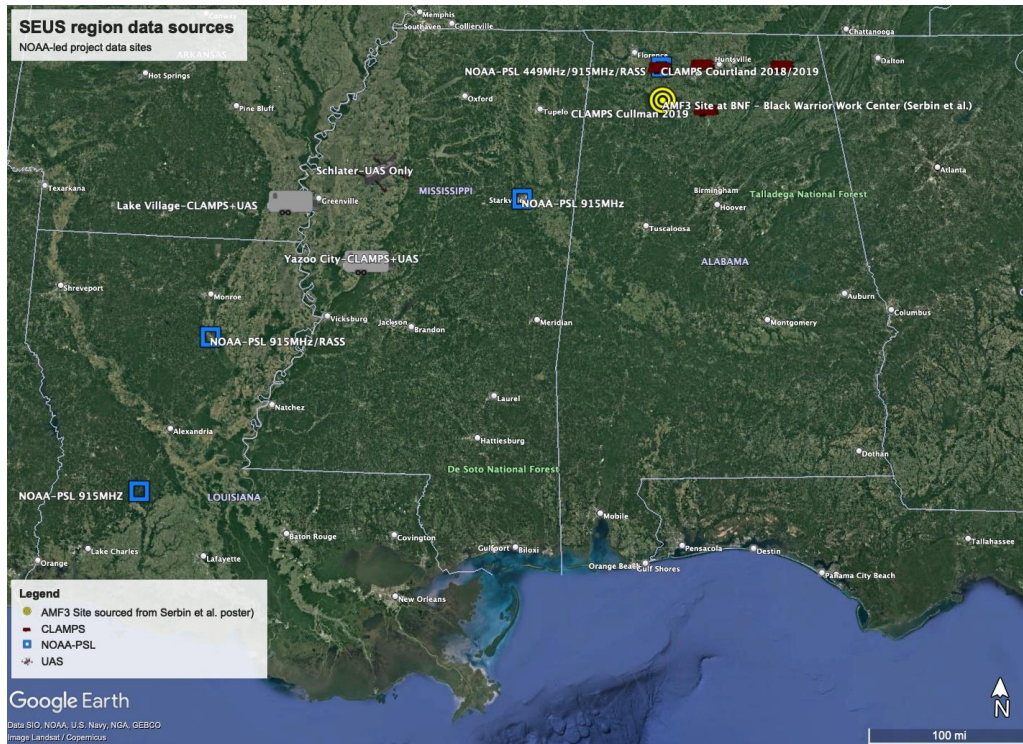


VORTEX-USA/PERiLS

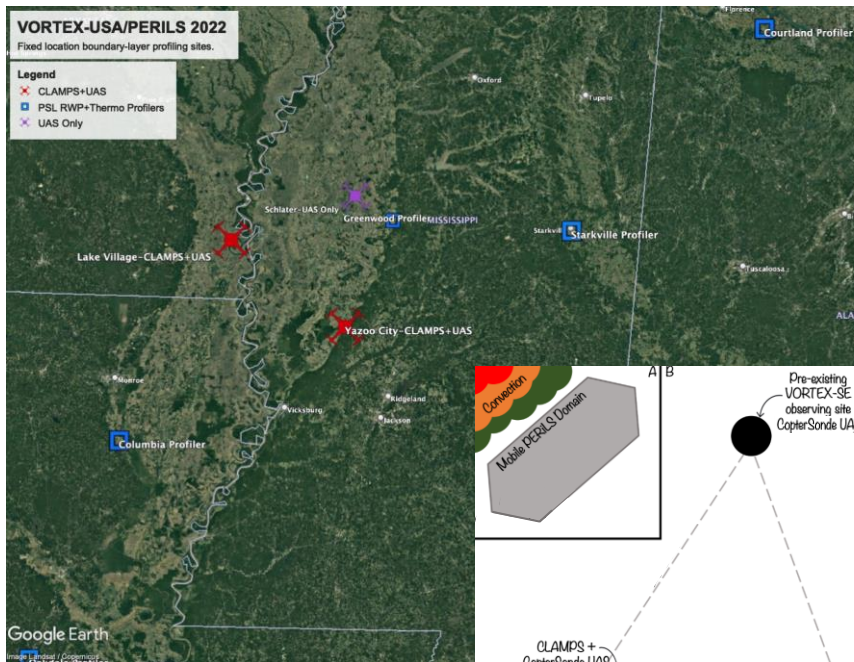
2015-2020 VORTEX-SouthEast

Cool season deployments of fixed facilities to North Alabama

Use these years of data to determine scales of motion and necessary observation spacing

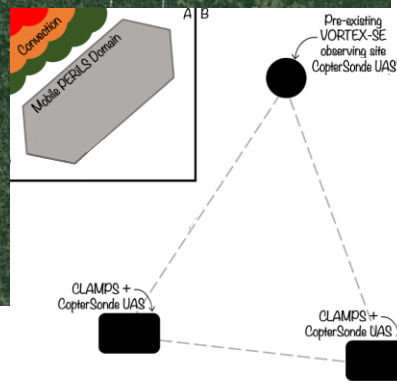


Innovation as motivation for PERiLS CONOPS



COA: 3 sites, 0–1.5km AGL

0–5000 feet AGL



Need: *network* low-atmosphere observations in *challenging environment* of southeastern US

VORTEX-SE findings: above-surface variability critical, 2016–2019 remote sensor profiling obs suggested ~50 km min. spacing, 90 km spacing

PERiLS opportunity: deploy prototype network with *network-in-network* framework

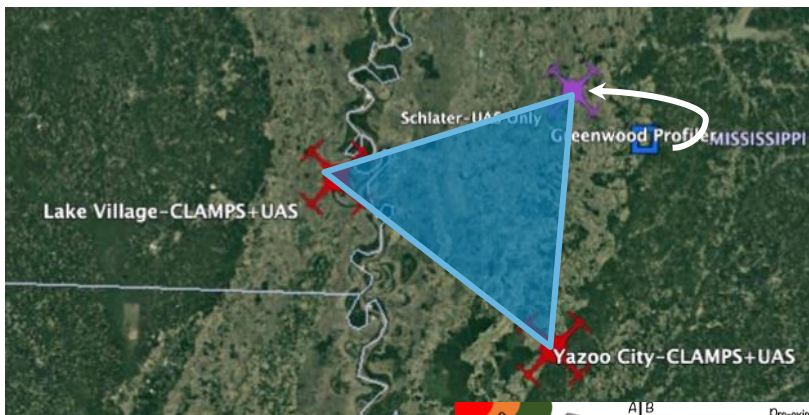
- Finer spacing within broader coarse deployment
- Mix obs types; remote sensor types and **UAS**
- Enables experiments with adaptable network concepts, testing data assimilation density needs, evaluating impacts of mixed obs networks, etc...



PERiLS as a next-generation observation network testbed



Innovation as motivation for PERiLS CONOPS



Need: *network* low-atmosphere observations in *challenging environment* of southeastern US

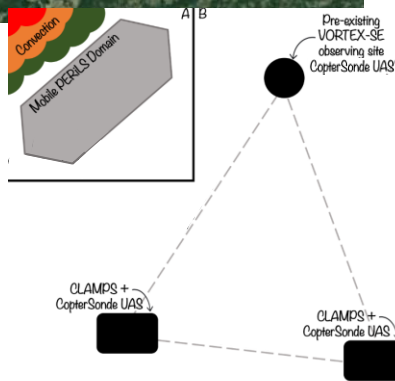
VORTEX-SE findings: above-surface variability critical

PERiLS opportunity: deploy prototype network with *network-in-network* framework

- **Networked deployment strategy** enables interesting analyses
- **Exploring development of products for future next-generation networks, including 3D networks**

Green's Theorem

$$\oint_C P dx + Q dy = \iint \left(\frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right) dA$$



Green's Theorem: Wagner et. al. (2022)

- Used HRRR profiles and data from remote profiler locations at the ARM SGP central and satellite facilities to evaluate the method
- Decent agreement between quantities derived from HRRR and ARM data
- Found small perturbations to the location of a vertex could impact calculations, especially if the magnitudes were small to begin with

Observing Profiles of Derived Kinematic Field Quantities Using a Network of Profiling Sites

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^a Space Science and Engineering Center, University of Wisconsin–Madison, Madison, Wisconsin

^b NOAA/Global Systems Laboratory, Boulder, Colorado

^c Department of Physics, Cleveland State University, Cleveland, Ohio

^d NASA Goddard Space Flight Center, Greenbelt, Maryland

(Manuscript received 7 May 2021, in final form 17 November 2021)

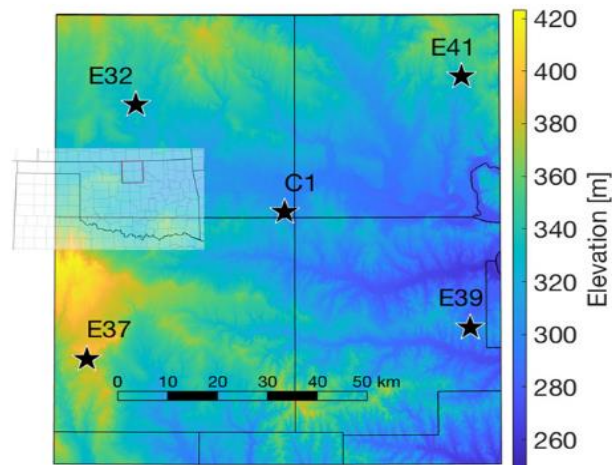
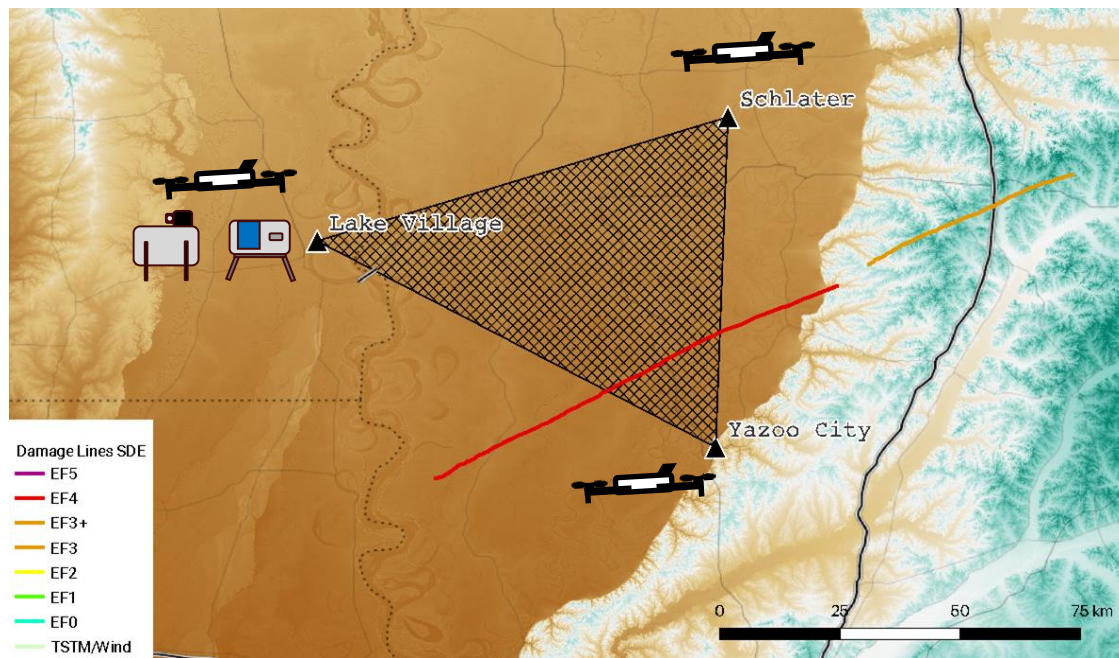


FIG. 1. Map of the ARM SGP domain, including the location of the Central Facility (C1) and the four extended facilities (locations starting with “E”), along with elevations (in m). The inset map shows the location of the domain within the state of Oklahoma.

Green's Theorem: Application

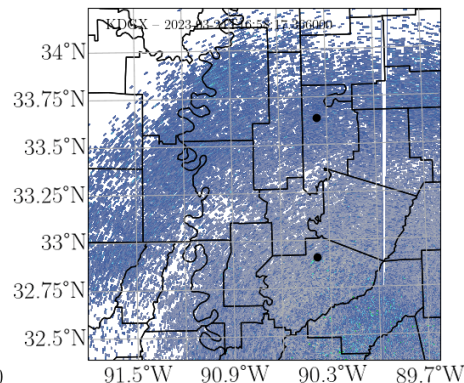
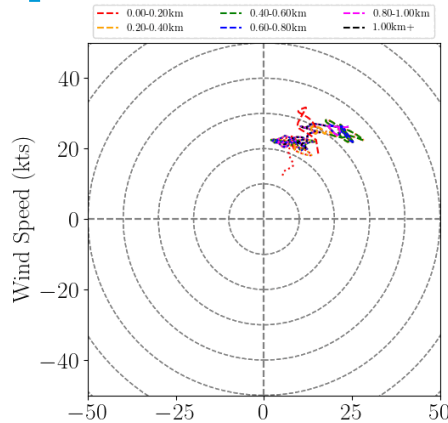
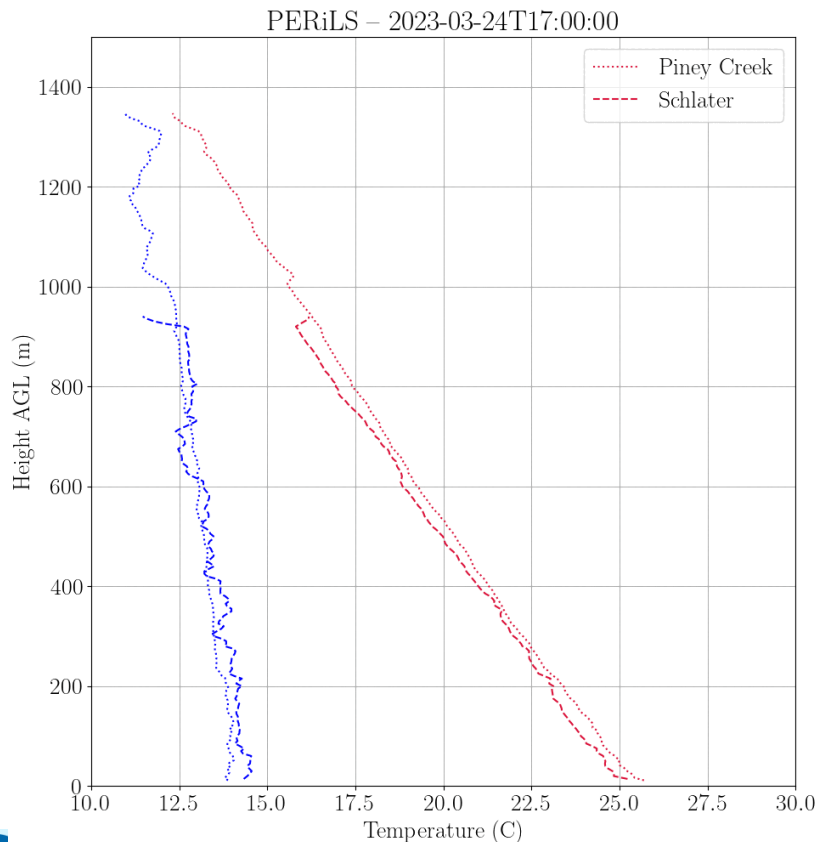
Rolling Fork Tornado

PERiLS mobile armada
deployed NNW
(Lake Village area)





Green's Theorem: Application



Each line is one Coptersonde site.

If a line is missing that site did not fly for that timestamp. Points correspondingly appear/disappear on radar plot

Different sites make it to different maximum heights due to wind tolerance and visual line of site limits (cloud base)

LV= WEST PC= SOUTH
SCH= NORTH



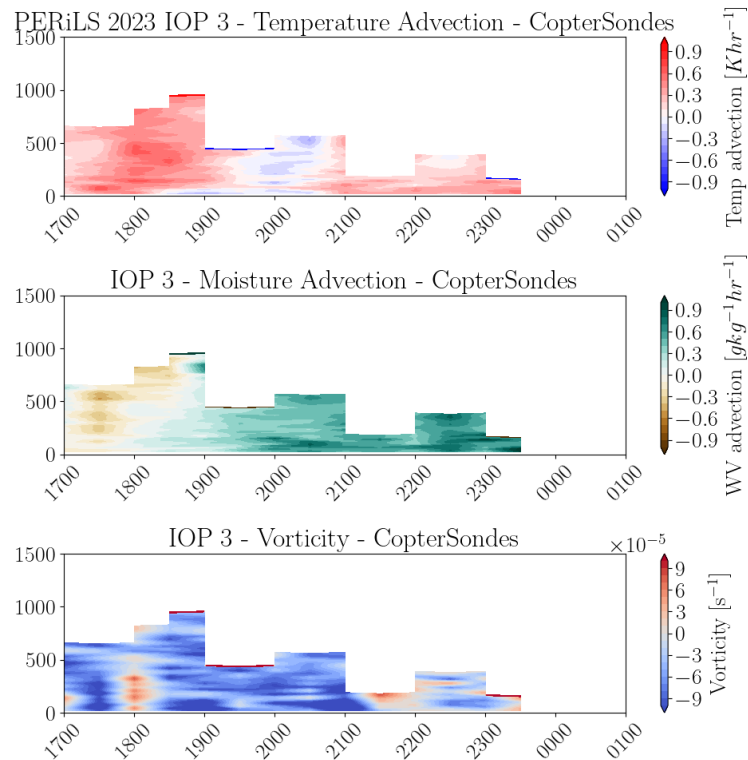


Green's Theorem: Application

Variable profile depth/information content degrades the success of this approach for basic CopterSonde data

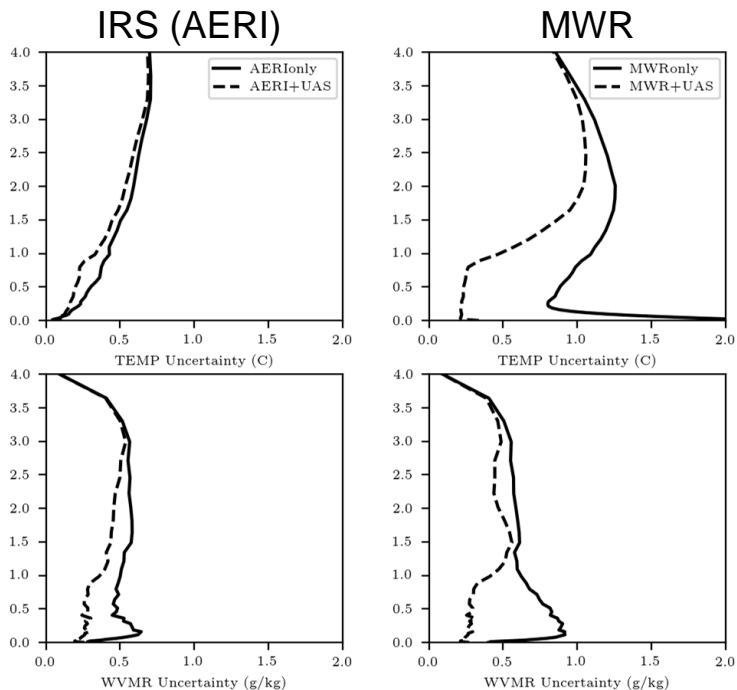
Southeast US complexity invites innovation to meet mission needs:

- Observation platforms
- Observation strategies
- **Observation analysis products**





TROPoe – Tropospheric Remotely Observed Profiling via optimal estimation



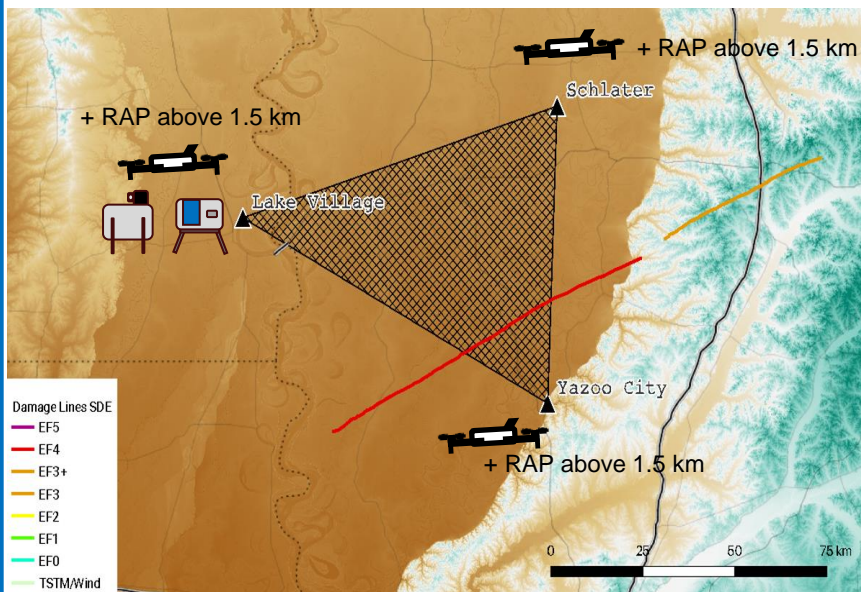
Bell, 2021

- Developed primarily for performing thermodynamic retrievals from IRS and MWRs
- Method can be generalized to take **multiple types of input**
- Provides a way to **create similar datasets from dissimilar data**, with uncertainty baked in

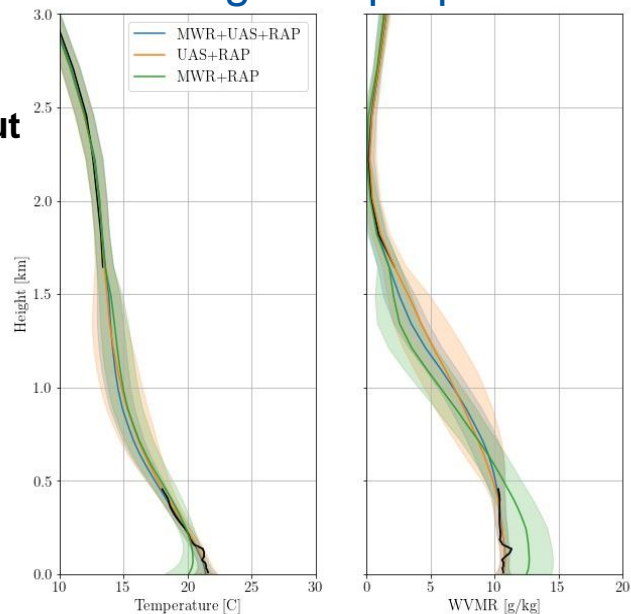


TROPoe – Tropospheric Remotely Observed Profiling via optimal estimation

- NOAA Rapid Refresh (RAP) Model above 1.5 km
- TROPoe can take any combination of instruments as long as a proper forward model is available



But what about the winds?





WINDoe

A **new OE method** developed by Dr. Josh Gebauer can retrieve wind profiles from dissimilar wind profiling platforms and data streams (*pub under review*)

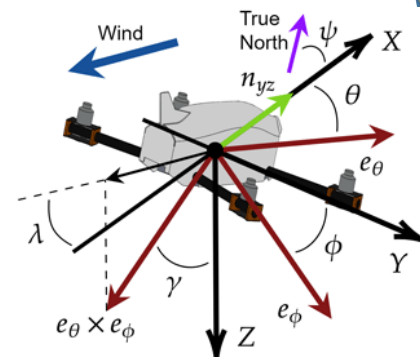
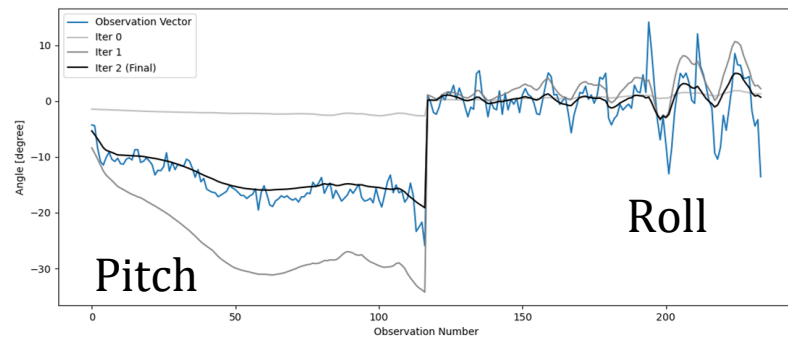
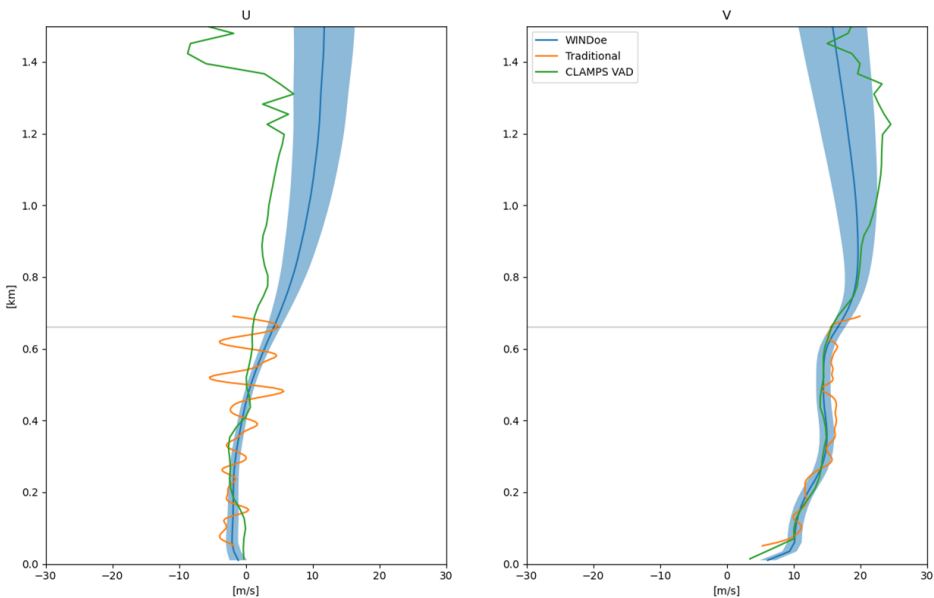


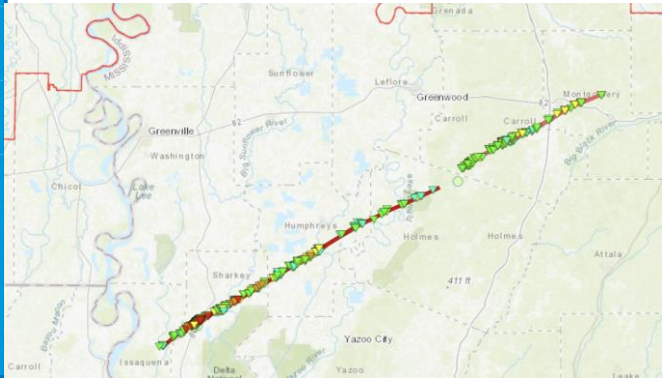
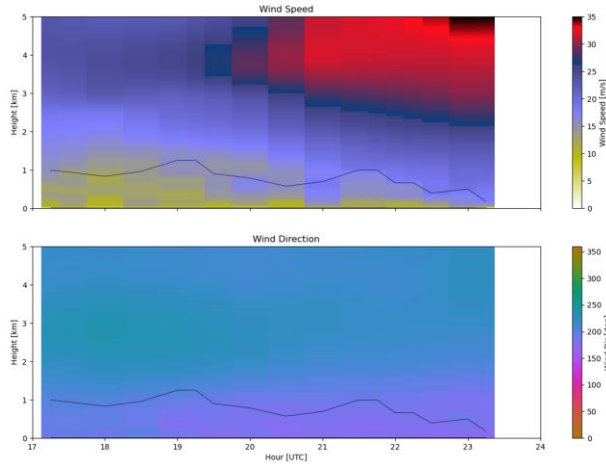
Figure from Segales et al. (2020)



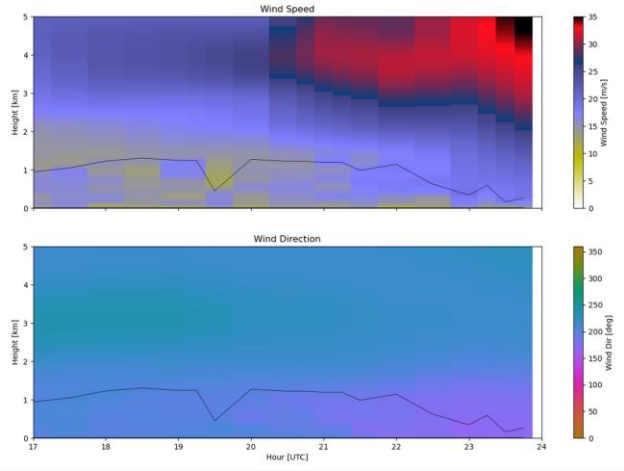


WINDoe examples

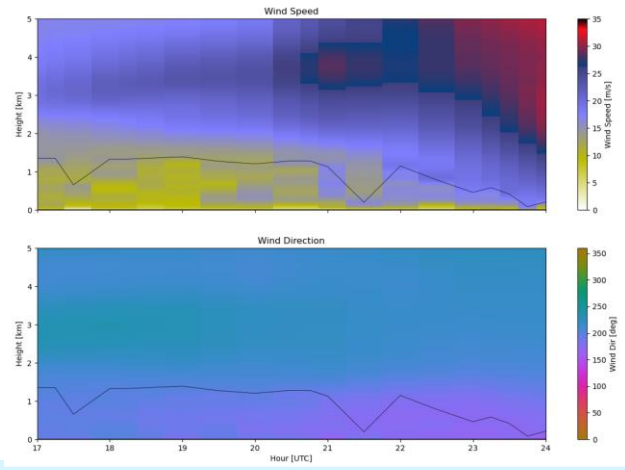
Lake Village



Schlater



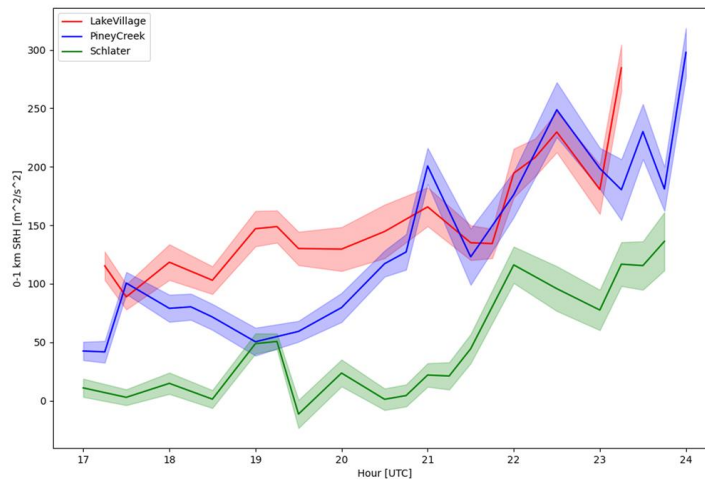
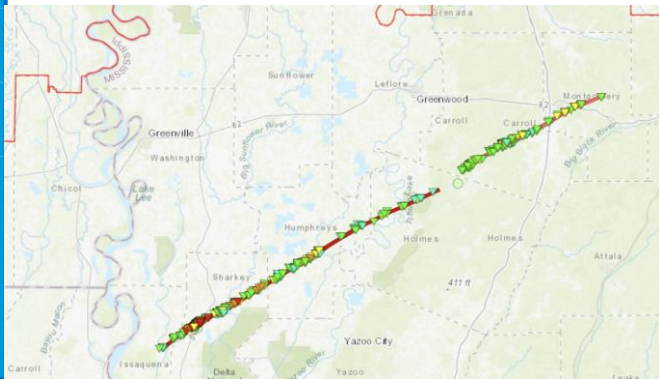
Piney Creek



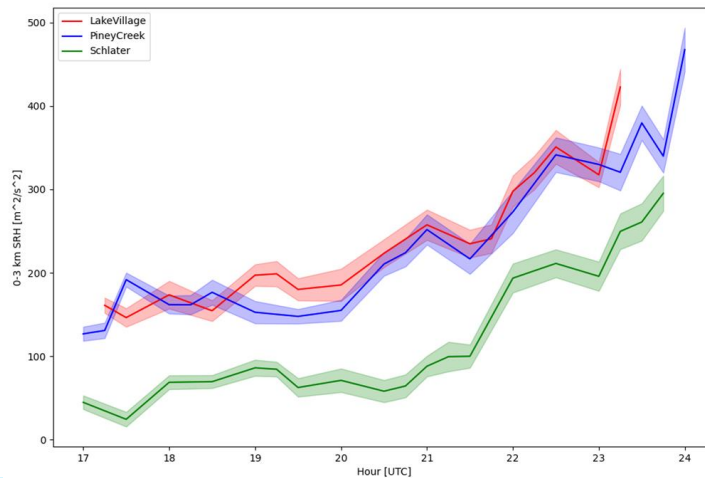


WINDoe examples

Through Monte Carlo sampling of the posterior covariance matrix, we can obtain uncertainties for derived indices using the retrieved profile



0-1 km SRH



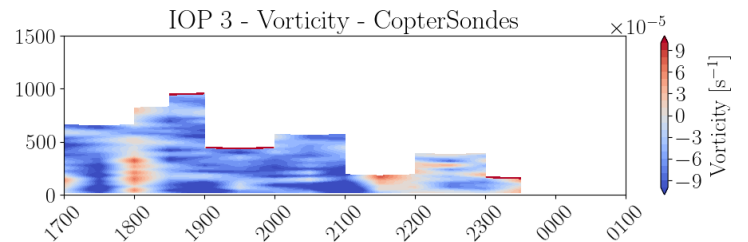
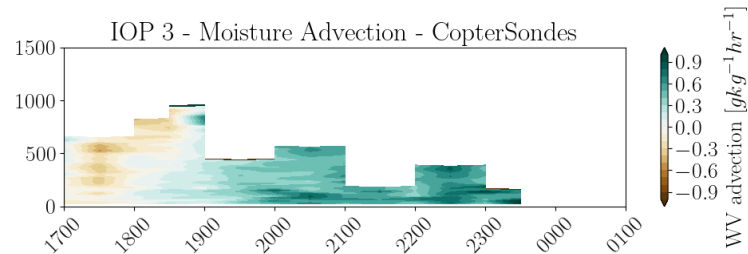
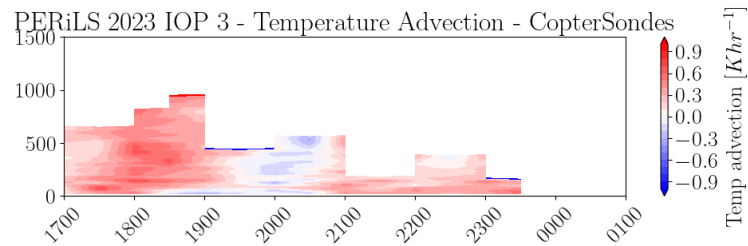
0-3 km SRH





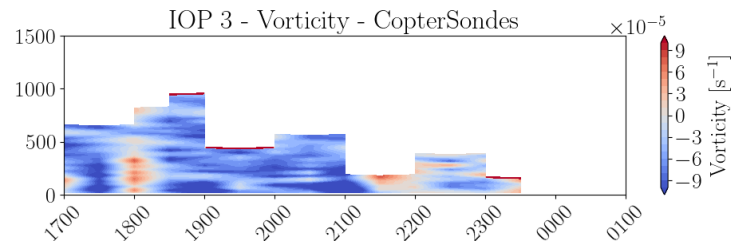
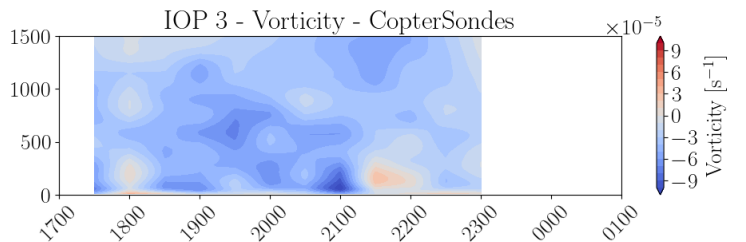
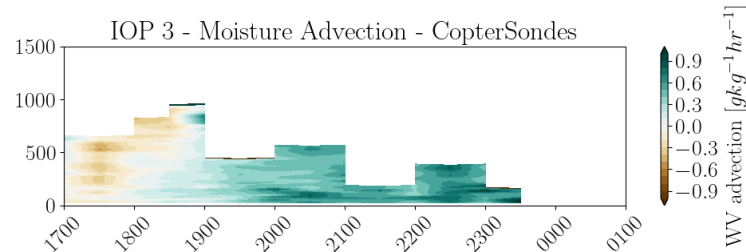
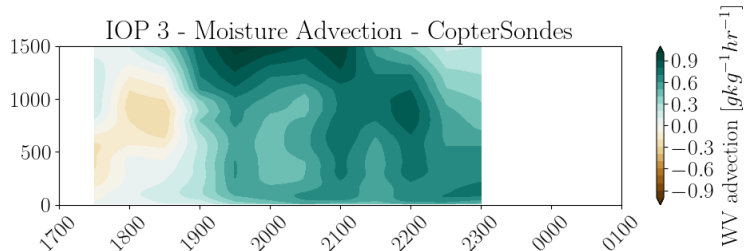
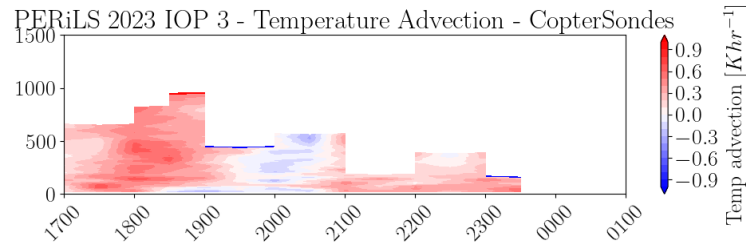
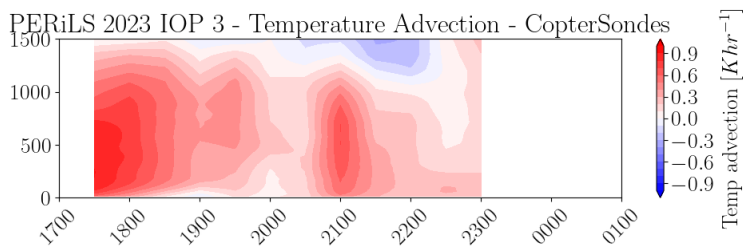
Green's Theorem: TROPoe + WINDoe

- NOAA Rapid Refresh (RAP) Model above 1.5 km
- TROPoe can take any combination of instruments as long as a proper forward model is available
- Combined with WINDoe, can rerun advection analysis on retrieved profiles





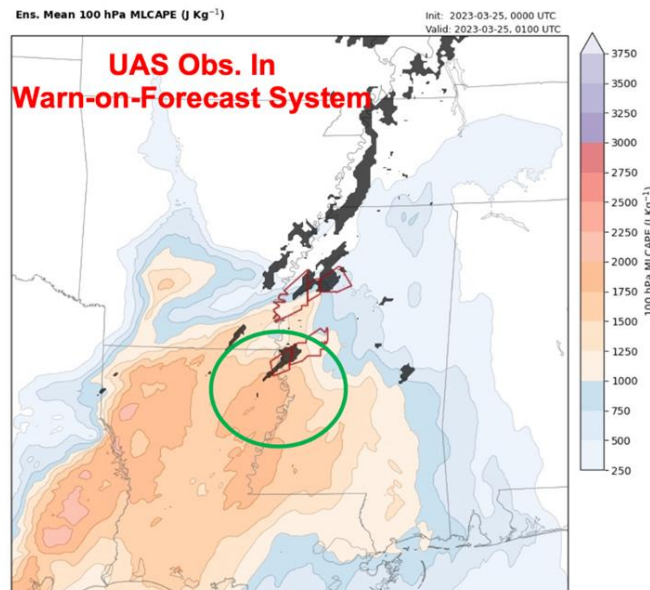
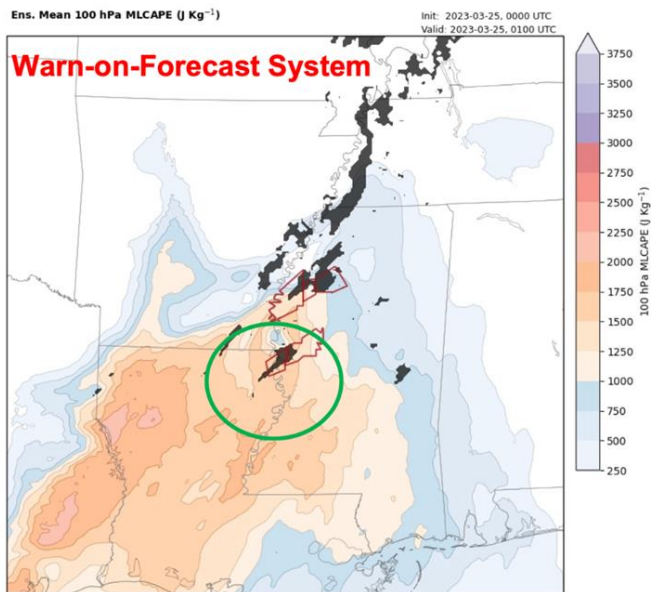
Green's Theorem: TROPoe + WINDoe



Data Assimilation Experiments

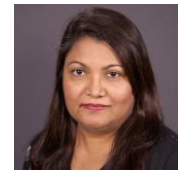


1-hr Fcst Ensemble Mean 100 hPa MLCAPE (J Kg⁻¹)



warning polygons in red

UAS experiment increases MLCAPE in inflow to Rolling Fork storm



CIWRO Scientist
Dr. Nusrat Yussouf



MS Student
Jordan Tweedie

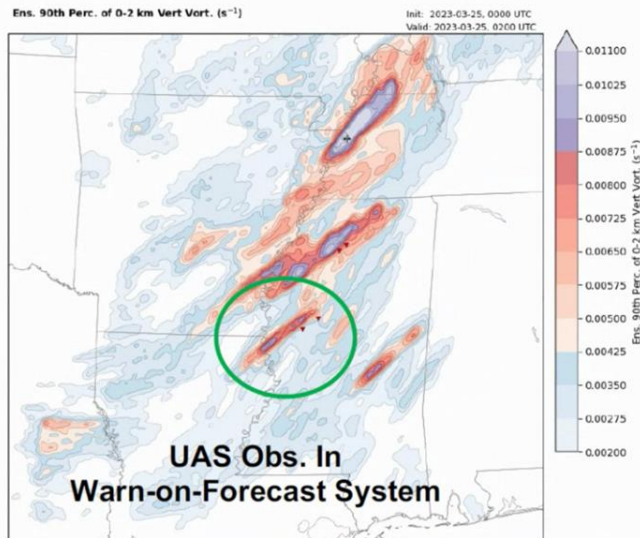
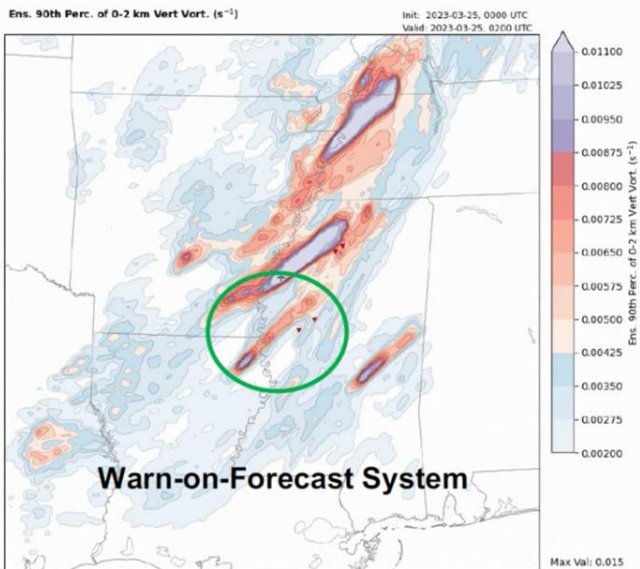




Data Assimilation Experiments



2-h Forecast Ensemble 90th Percentile of 0-2 km Vertical Vorticity (s^{-1})



Improved location of Rolling Fork track and forecast severity (and correctly tamps down vorticity in northern track)

Red triangles: tornado report



CIWRO Scientist
Dr. Nusrat Yussouf



MS Student
Jordan Tweedie

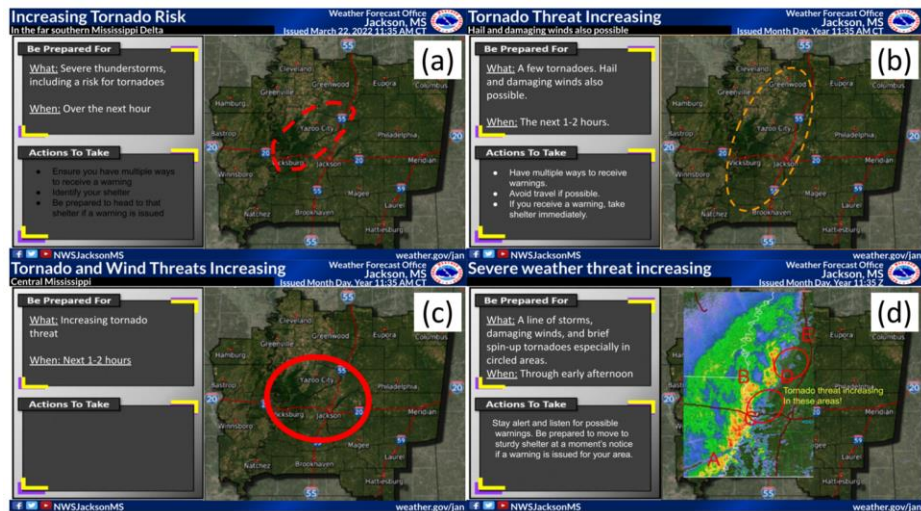




R20 – Stakeholder/End User Needs

PERiLS 2022 CopterSonde data evaluated in NWS forecast exercises

Between the second (1505 UTC) and third (1535 UTC) time steps, and then between the fourth (1605 UTC) and last (1635 UTC) time steps, only updates from the radar and CopterSonde were provided. P6 described the benefit of having observations between updates in the RAP, such that “the CopterSonde provided data that helped me determine that the environment at Point D had changed over the past 30 minutes and had become more supportive of a tornado threat.” Most of the experimental groups’ responses to the survey at this time, focused on the use of CopterSonde data.



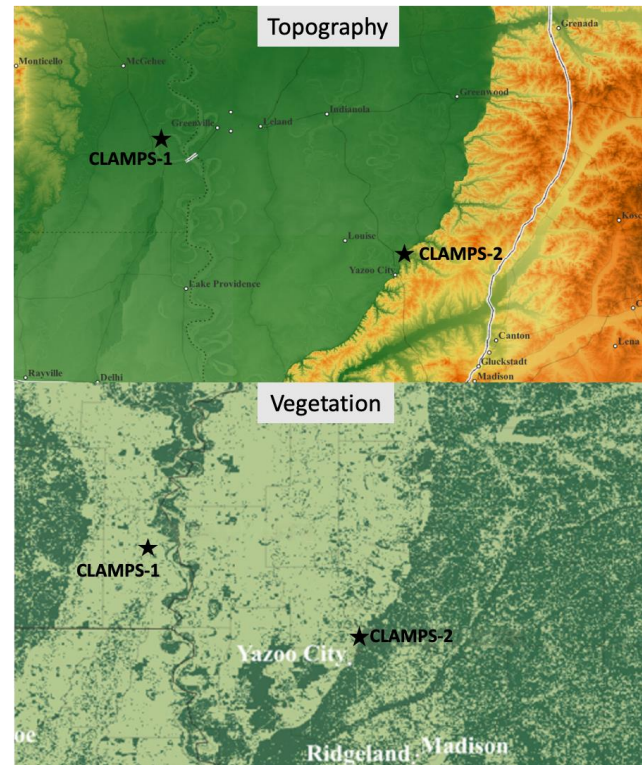
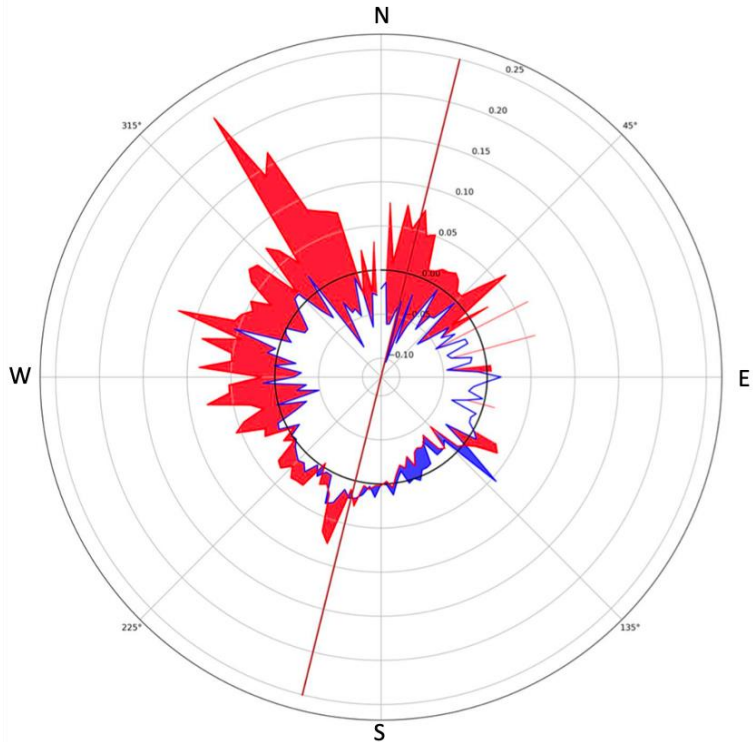
Connor Bruce, 2023: Exploring CopterSonde Use for National Weather Service Operations

OU Master Thesis



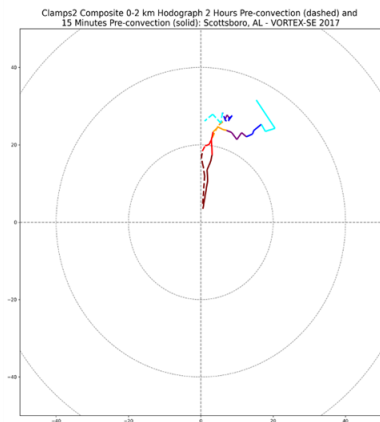
Process Understanding – Terrain Influence

CLAMPS2 (Red) and CLAMPS1 (Blue) Magnitude of Vertical Motion vs. Wind Direction
(Lowest 1km) 3/1/22 - 4/24/22

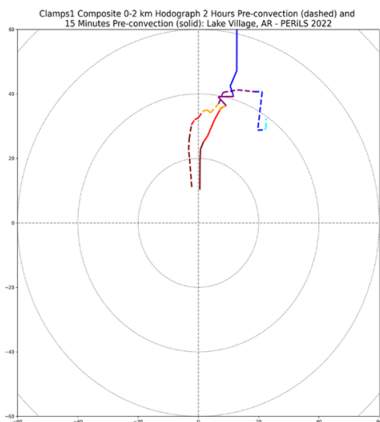


Process Understanding – Terrain Influence

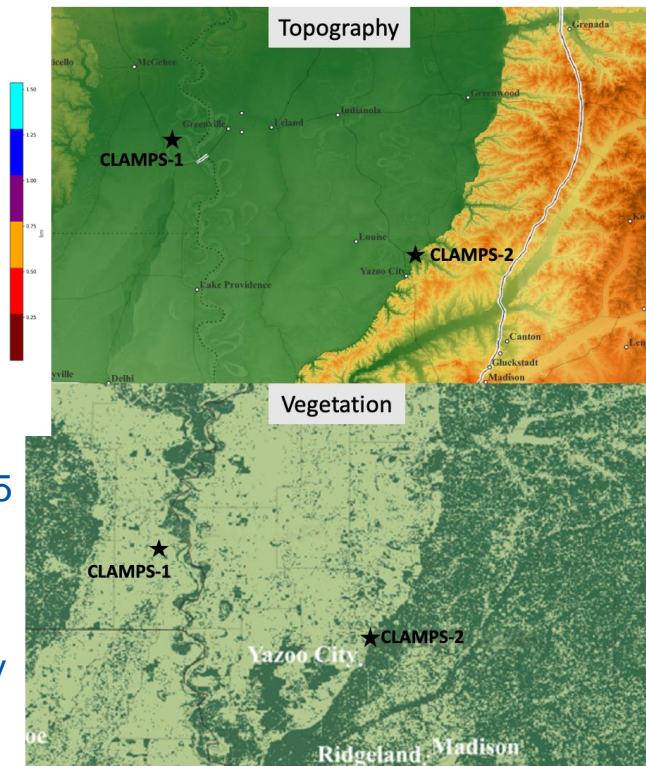
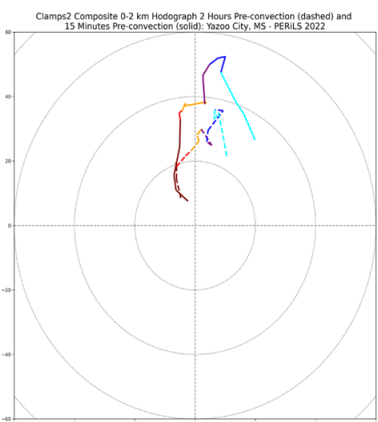
Scottsboro, AL:



Lake Village, AR:



Yazoo City, MS:

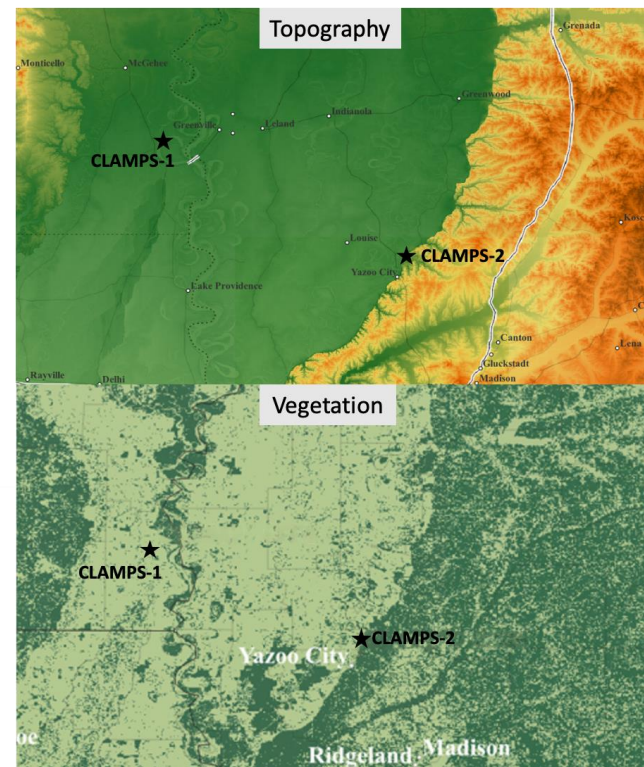
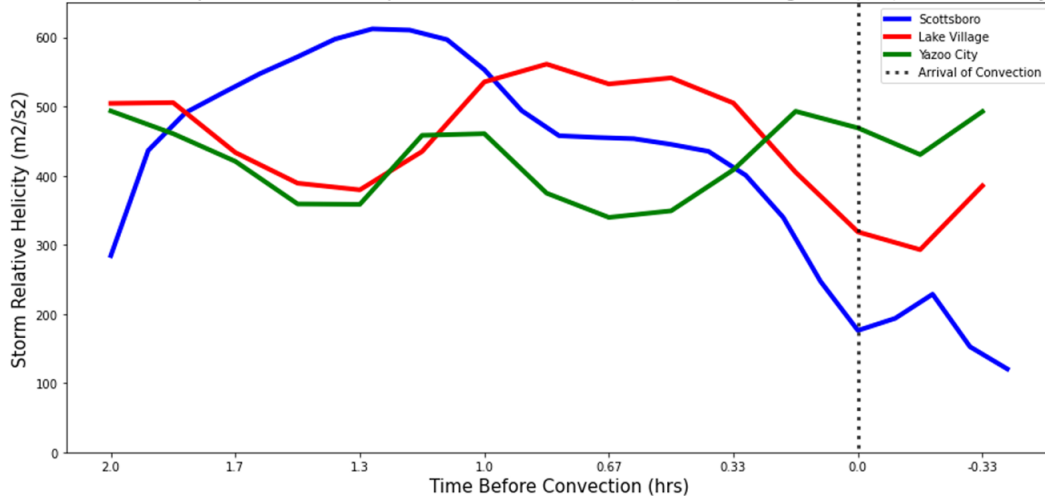


- Yazoo City composite exhibits much more **curvature** in lowest ~0.5 km due to terrain-induced backing of near-surface flow. This promotes more streamwise oriented vorticity
- There is notable **acceleration of 0-1 km shear vector** between 2 hours pre-conv, and 15 minutes pre-conv in Yazoo City composite while others reflect little change



Process Understanding – Terrain Influence

CLAMPS 0-1 km SRH 2-hr pre-convective Composites at Scottsboro, AL (blue), Lake Village, AR (red), and Yazoo City, MS (green)



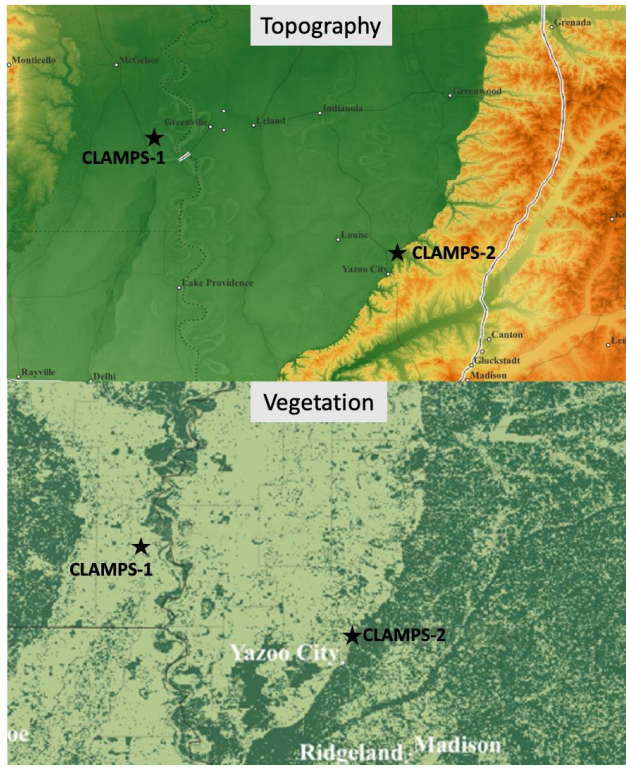
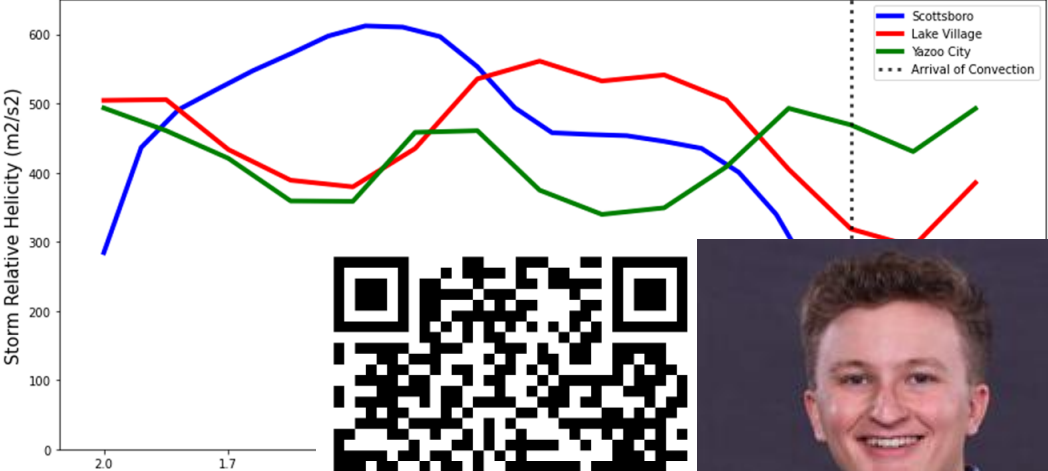
0-1 km SRH increases during the ~45 minutes leading up to the arrival of convection at the Yazoo City site while it decreases during that same period at the other sites. *This is possibly due to the interaction between the terrain gradient and the backing winds that occurs in response to the storm inflow.*





Process Understanding – Terrain Influence

CLAMPS 0-1 km SRH 2-hr pre-convective Composites at Scottsboro, AL (blue), Lake Village, AR (red), and Yazoo City, MS (green)



Recorded Seminar:
bliss.science/seminar/20230508-matthew-ammon/





PERiLS PBL Profiling: *CLAMPS and CopterSonde UAS*

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Affiliated Assistant Professor–OU School of Meteorology

Email: elizabeth.smith@noaa.gov / Social media: @eeeeelizzzzz

Tyler Bell, Joshua Gebauer, Tony Segales – OU CIWRO





Looking ahead

Ongoing work and what's next



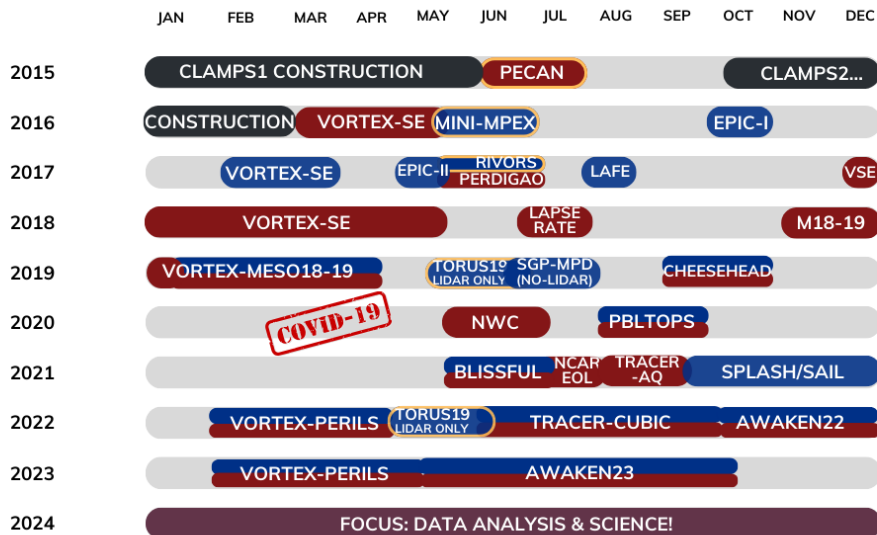
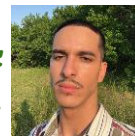
CLAMPS TIMELINE



LEGEND

- CLAMPS1
- CLAMPS2
- NIMBLE
- CO-DEPLOY
- SPLIT DEPLOY

Created by OU UG
Victor Alvarez



Home CLAMPS-1 CLAMPS-2 NSSL CIWRO

CLAMPS-1 Data Viewer Mon, 18 Sep 2023 15:38:53 GMT

Filter by... Select... LP

August 7, 2023
[DLP](#) [AED](#) [GLVAD](#) [VAD](#) [CONTR](#) [NOUWKEEFPND](#)

August 6, 2023
[DLP](#) [AED](#) [GLVAD](#) [VAD](#) [CONTR](#) [NOUWKEEFPND](#)

August 5, 2023
[DLP](#) [AED](#) [GLVAD](#) [VAD](#) [CONTR](#) [NOUWKEEFPND](#)

August 4, 2023
[DLP](#) [AED](#) [GLVAD](#) [VAD](#) [CONTR](#) [NOUWKEEFPND](#)

August 3, 2023
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August 2, 2023
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August 1, 2023
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July 31, 2023
[DLP](#) [AED](#) [GLVAD](#) [VAD](#) [CONTR](#) [NOUWKEEFPND](#)

Data Availability Timeline
 AERICE
 DLP
 DLVAD

Vertical Velocity (High Sensitivity) C1 - 2023-08-04T00:00:00
 Vertical velocity (m/s)

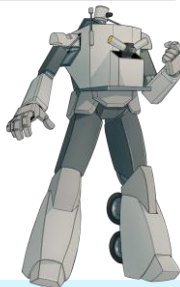
Wind Speed C1 - 2023-08-04T00:00:00
 wind speed (m/s)

Dewpoint C1 - 2023-08-04T00:00:00
 dewpoint (C)

Data selection
 Make desired selections below...
 DLPF
 Vertical Velocity (high)
 Doppler Lidar VAD
 Wind Speed
 TROPoe
 Dewpoint

Data Viewer THREDDS Data Access

Get started using our data with tools at bliss.science/resources/code





PRODIGEE-UAS



The CopterSonde UAS collects meteorological profiling observations on multiple projects at NSSL and CIWRO/University of Oklahoma. Since 2020, it has conducted **approximately 1,500 research flights**. Science & engineering staff at NSSL and CIWRO are leading a project supported by NOAA's UxSRTO called **PRODIGEE** to advance CopterSonde capabilities.

CURRENT	TARGET
WIND TOLERANCE: 22 M/S (50 MPH)	WIND TOLERANCE: 35 M/S (78 MPH)
MAX FLIGHT CEILING: 1.5 KM AGL	MAX FLIGHT CEILING: 3 KM AGL
VISUAL LINE OF SIGHT OPERATIONS	BEYOND VISUAL LINE OF SIGHT OPERATIONS

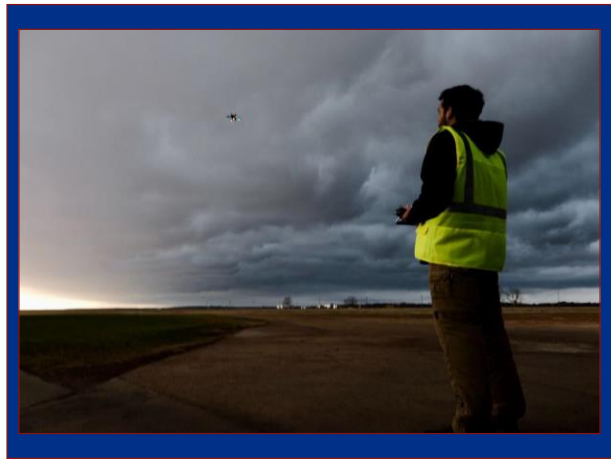
bliss.science/resources/sensing/coptersonde

CopterSonde flights are enabling rapid, in-situ, low-level profiling of thermodynamic and kinematic conditions in the atmosphere.

Many research directions are being explored.



- R&D of UAS platform and supporting software and hardware to increase flight capability and autonomy
- similarities, differences, and possible synergies between UAS-based and ground-based profiling techniques
- impacts and network needs for low-level, rapid profiles in data assimilation contexts
- basic science (e.g., knowledge development based on the new types of obs these platforms enable such as parcel residence times, convection initiation processes, etc.)

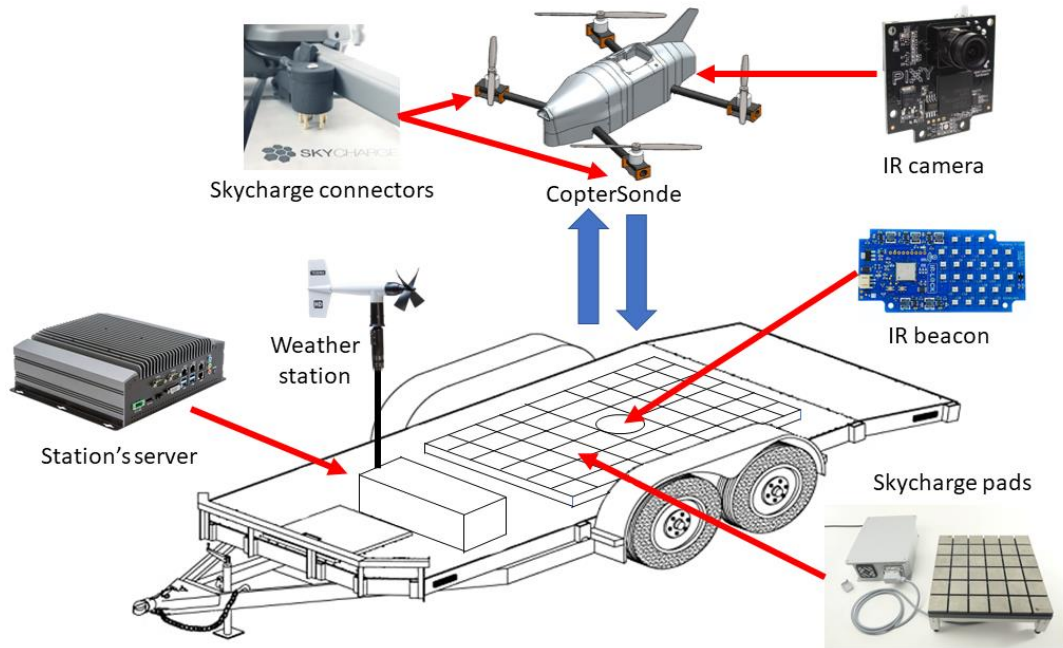




CIWRO – Precision Landing and Auto-Charging for Weather-Sensing UAS

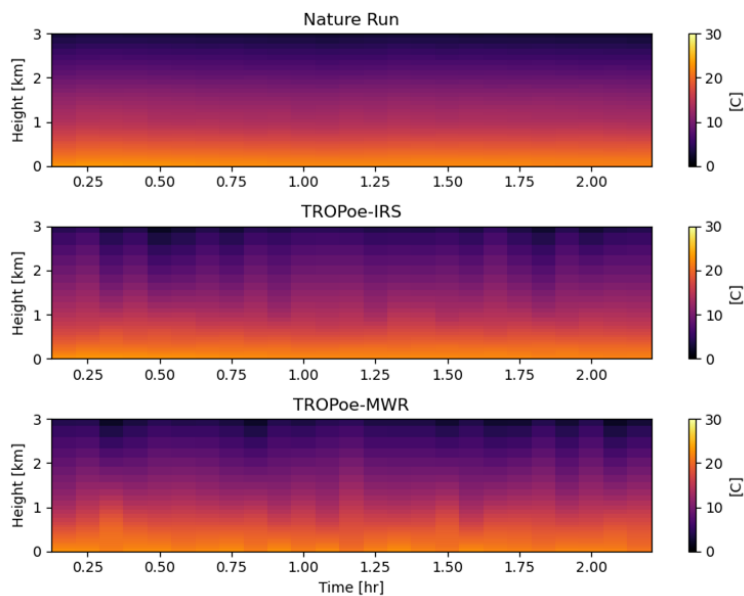
Key research goals:

1. Create a proof-of-concept platform for the future development of many supporting requirements (e.g. detect and avoid capabilities, surface station integration, fully remote launch and recovery, etc.) necessary to realize **fully autonomous operations** (i.e. the 3D Mesonet)
2. Continue to develop the **cloud-infrastructure** necessary to operate and monitor remote operations



WPO: Venturing into the Vertical—OSSES

This study proposes to conduct research that will facilitate the development of a vital boundary layer profiling mesonet, often referred to as a **3D mesonet**, that could fill the boundary layer data gap in current observation networks. **Remote and in situ platforms** such as infrared spectrometers, microwave radiometers, Doppler lidars, and weather-sensing uncrewed aircraft systems (UAS) can provide boundary layer observation profiles, but the **optimal design of such a network venturing into the vertical remains unknown**.



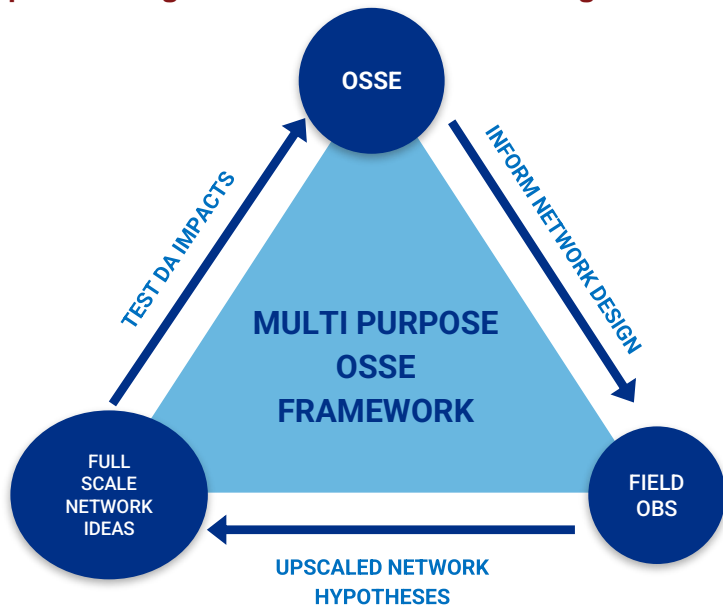
Key research goals:

1. **Observing system simulation experiments (OSSEs) with high-quality observation simulators** to replicate directly observed variables from remote profilers, UAS.
2. Field deployments with **up to 12 weather UAS** to replicate operational boundary layer profiling mesonet in high-impact weather environments.
3. Use OSSEs and field deployments to **test analysis and retrieval techniques** that could be performed in near-real time.
4. Leverage high-resolution flow-simulations and data from past and current CopterSonde deployments to **improve upon the CopterSonde design for operational profiling**.



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PERiLS PBL Profiling: *CLAMPS and CopterSonde UAS*

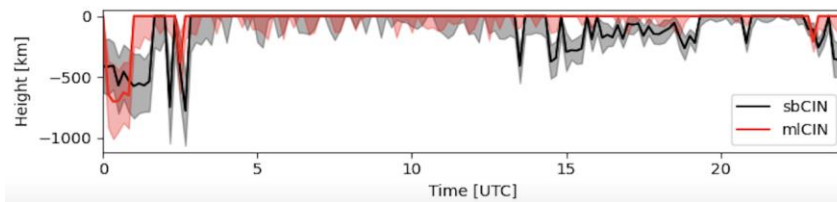
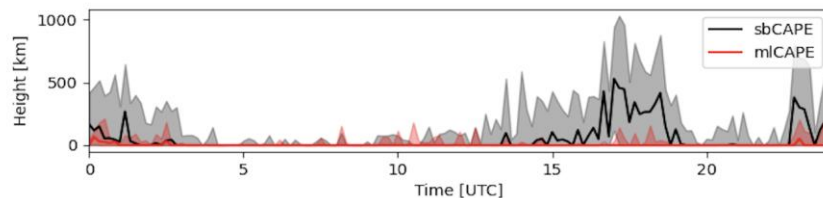
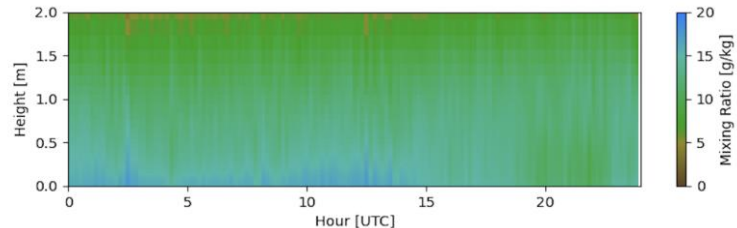
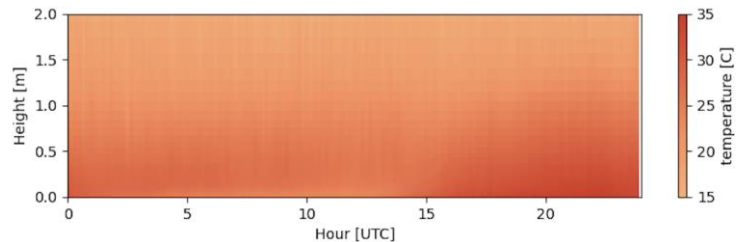
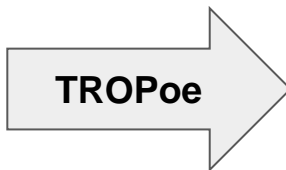
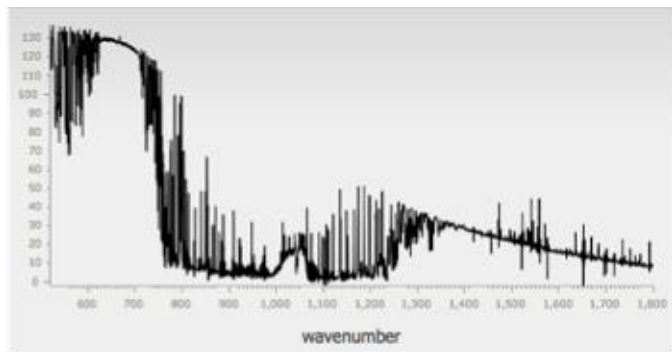
Dr. Elizabeth Smith Research Meteorologist–NOAA National Severe Storms Laboratory
Affiliated Assistant Professor–OU School of Meteorology

Email: elizabeth.smith@noaa.gov / Social media: @eeeeelizzzzz

Tyler Bell, Joshua Gebauer, Tony Segales – OU CIWRO



TROPoe: Tropospheric Remotely Observed Profiling via Optimal Estimation



Thermodynamic optimal estimation retrieval developed and maintained in collaboration with Global Systems Laboratory.

Very flexible retrieval system that works with:

- Infrared spectrometers
- Microwave radiometers
- Micropulse differential absorption lidar
- Radio acoustic sounding systems
- CopterSondes
- Radiosondes
- Numerical weather prediction

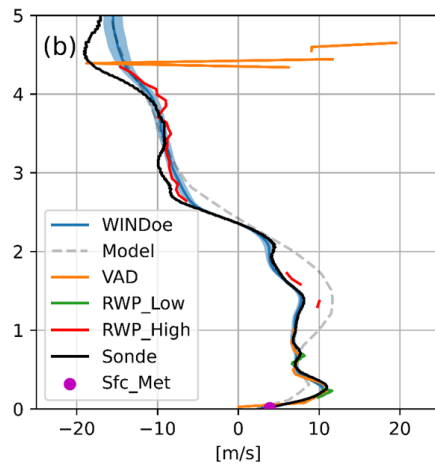
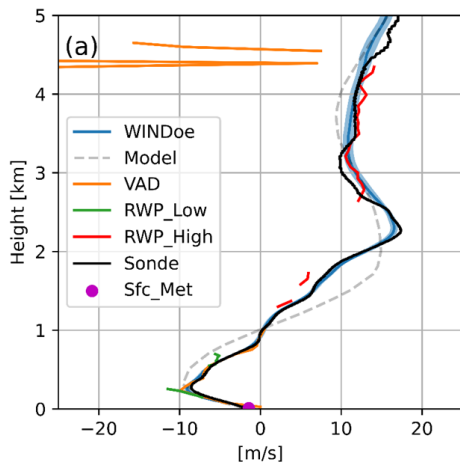
WINDoe: Wind via Optimal Estimation

Newly developed wind profile optimal estimation retrieval designed to be a complement to TROPoe. Developed by CIWRO/NSSL staff.

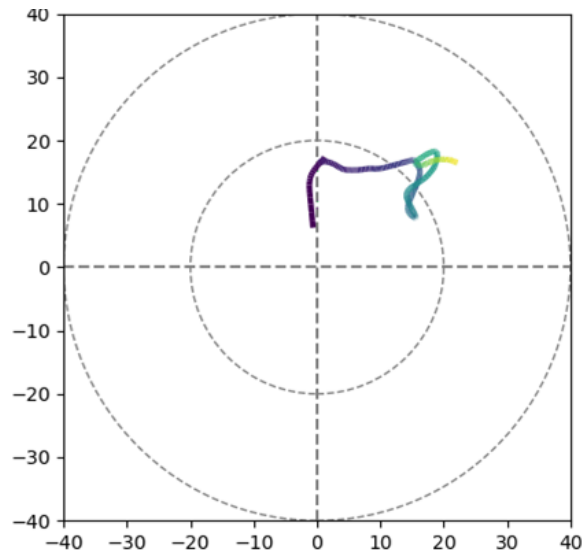
The technique allows for information content from wind profiling instrument to be used to the fullest extent and enables combined data products from:

- Doppler lidar
- Radar wind profiler
- CopterSondes
- Soundings
- Models

Example Combined WINDoe Retrieval at ARM-SGP Site



WINDoe retrievals on 19 April 2023



Code available for OAR at:

<https://github.com/OAR-atmospheric-observations/WINDoe>



CopterSonde UAS

Technical Specs

All-up weight:

2 kg

Hover time:

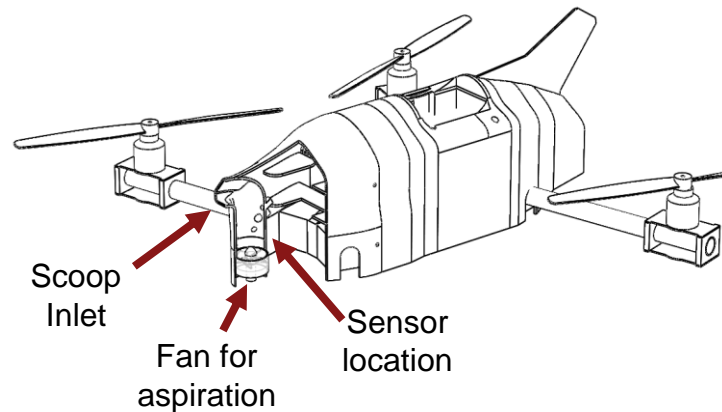
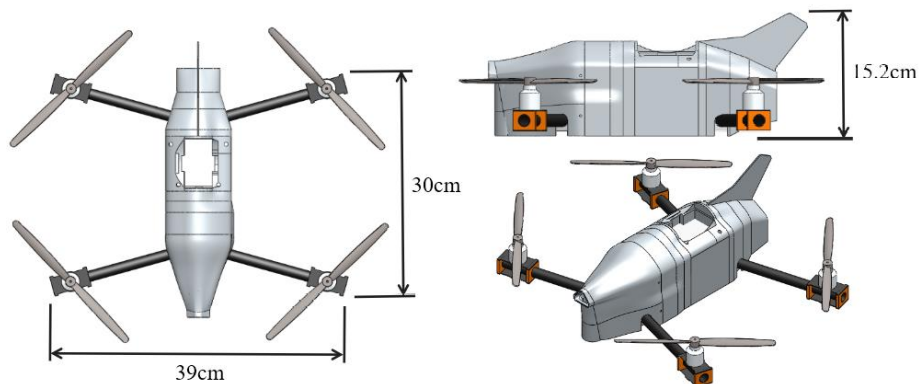
18 min

Max. mean wind: 22 m/s

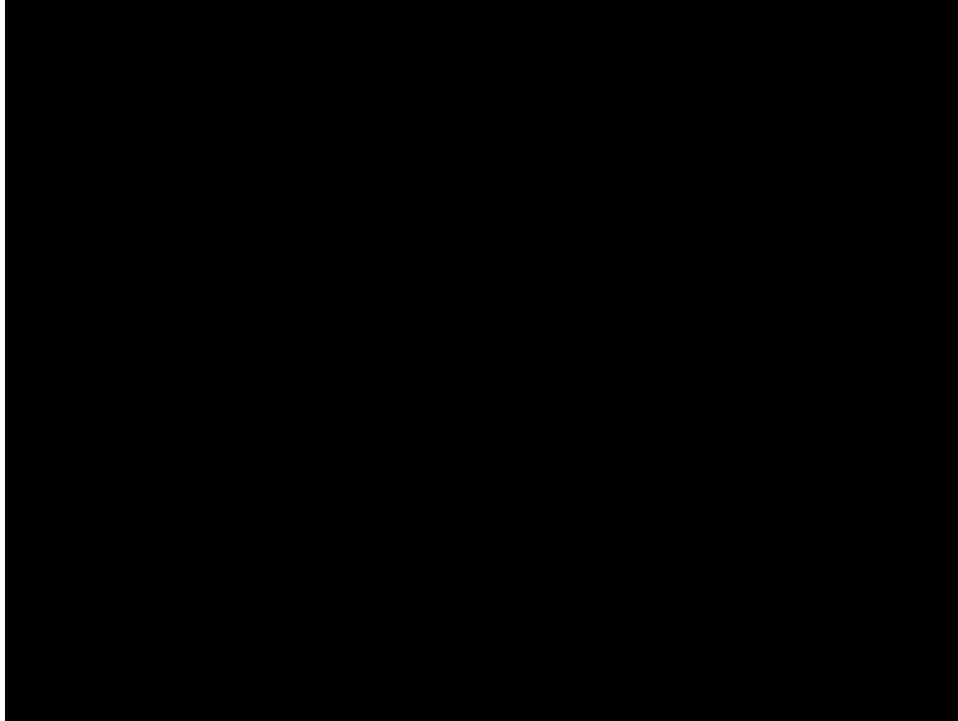
Max. wind gust: 26 m/s

Max. altitude (AGL): 1500m

Max. const. current: 61.5 A



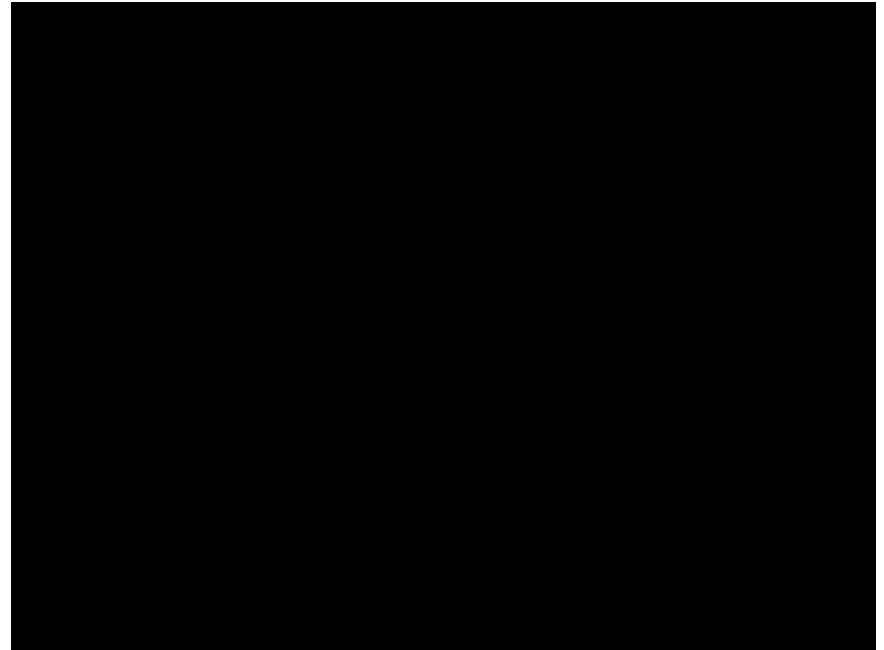
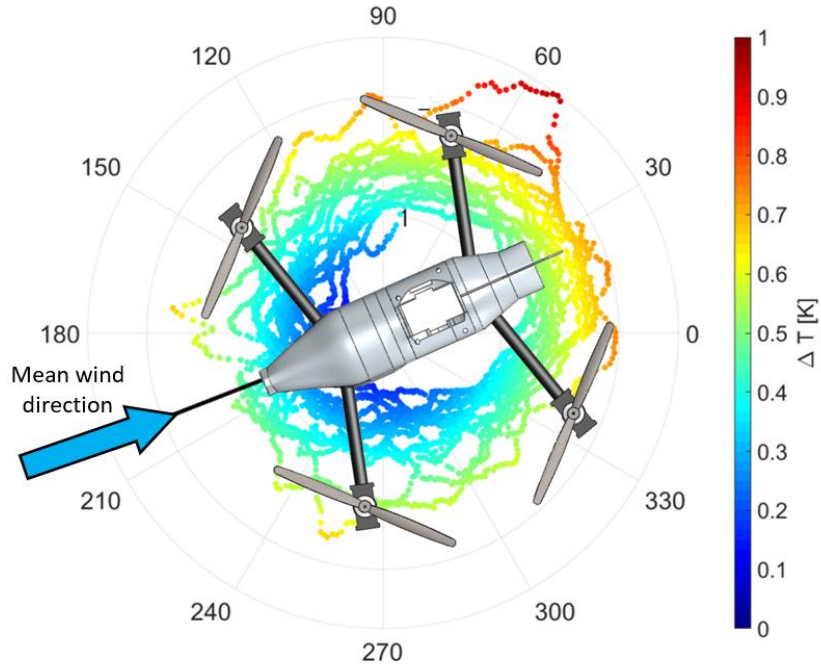
CopterSonde Comparisons



CS3D vs. Radiosonde	RMSE	R
Temperature	0.430 K	0.995
Relative humidity	2.548 %	0.907

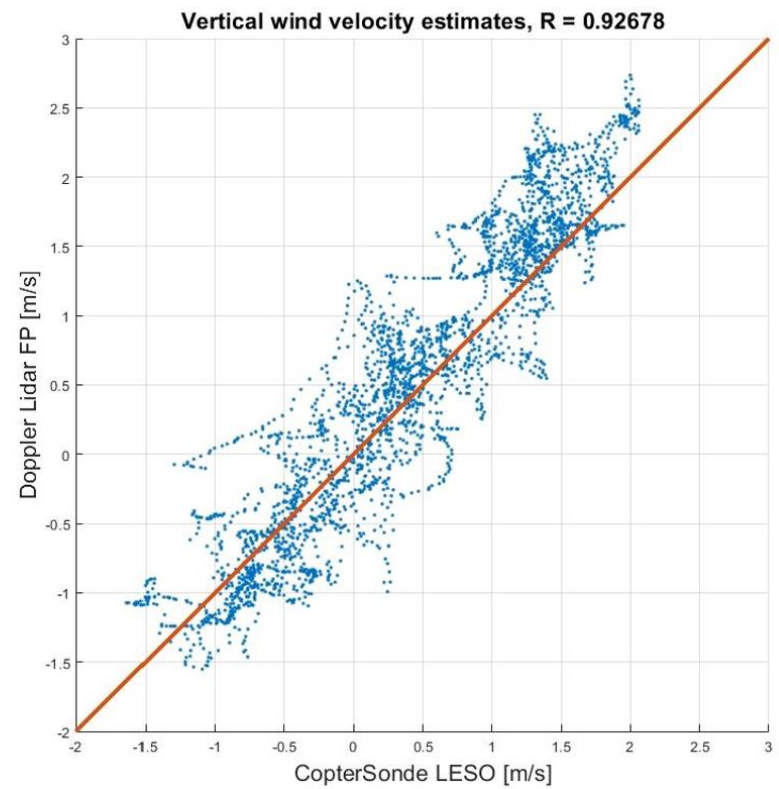
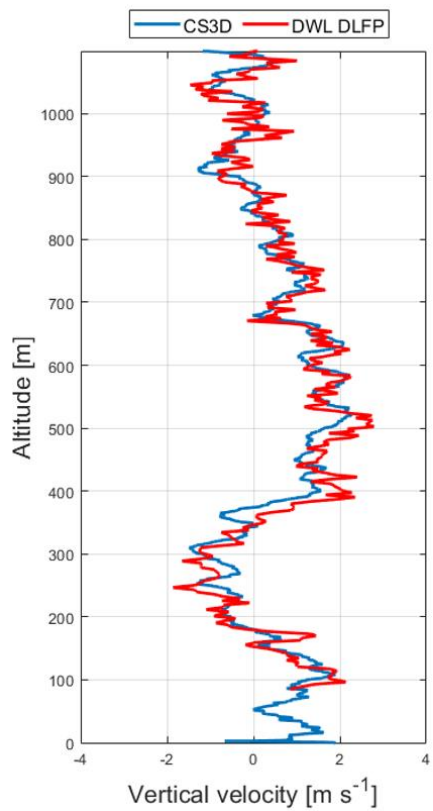
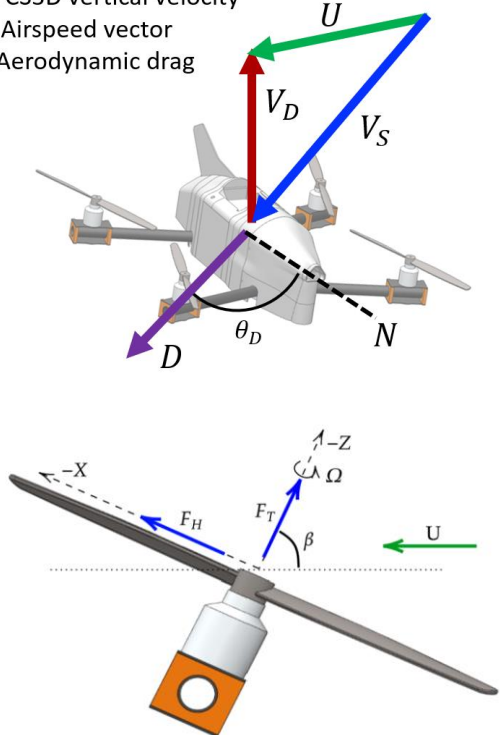
CopterSonde Thermodynamics

Wind vane function significantly helps mitigating sources of measurement errors



CopterSonde Vertical wind estimation

U : Wind velocity
 V_D : CS3D vertical velocity
 V_S : Airspeed vector
 D : Aerodynamic drag



PERiLS 2022–2023 Operations

Variable	All Sites	Yazoo City	Schlater	Lake Village
Max altitude (m)	1380	1380	1300	1247
Avg altitude (m)	491	572	514	393
Total flight count	347	119	111	103
Total operations time	44:15:19			

The Incidents...



Green's Theorem Approach

$$\oint_C P dx + Q dy = \iint \left(\frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right) dA$$



$$\frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \approx \frac{\sum (\bar{P}\Delta x + \bar{Q}\Delta y)}{A}$$

$$-\mathbf{V} \cdot \nabla \alpha = -\left(u \frac{\partial \alpha}{\partial x} + v \frac{\partial \alpha}{\partial y} \right)$$



$$-\mathbf{V} \cdot \nabla T = -\left(u \frac{\partial T'}{\partial x} + v \frac{\partial T'}{\partial y} \right) \approx \frac{-\sum \bar{T}'(\bar{u}\Delta y - \bar{v}\Delta x)}{A}$$

$$-\mathbf{V} \cdot \nabla q = -\left(u \frac{\partial q'}{\partial x} + v \frac{\partial q'}{\partial y} \right) \approx \frac{-\sum \bar{q}'(\bar{u}\Delta y - \bar{v}\Delta x)}{A}$$

$$\zeta = \frac{\partial v}{\partial x} - \frac{\partial u}{\partial y} \approx \frac{\sum (\bar{u}\Delta x + \bar{v}\Delta y)}{A}$$

Per Wagner et. al. (2022), since the calculation depend on the scalar magnitude, the mean scalar value of the vertices needs to be removed prior to calculating advection to be properly scaled





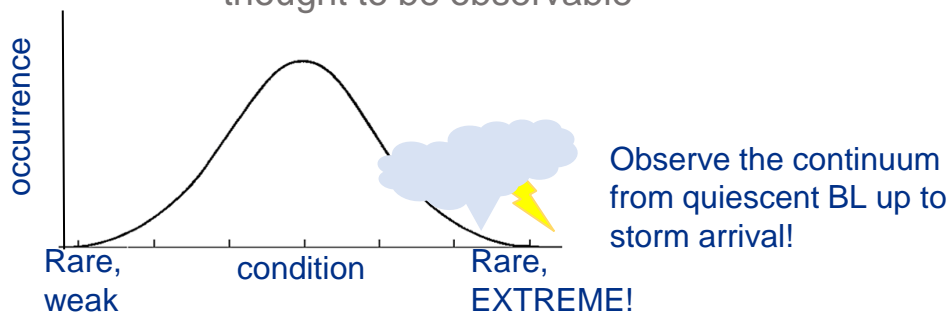
Innovation as motivation for PERILS CONOPS



Colocated with CLAMPS remote sensing boundary layer profiler (or near other profiler site)



1. CopterSondes begin profiling 8 hours prior to expected storm arrival
2. Coordinated flights occur every 30 minutes, unless the cadence is changed by the mission commander
3. Cadence may increase (at all sites) to 15-minute if a site is near-storm or another interesting weather feature is thought to be observable





VORTEX-USA/PERiLS



PhD student
Tyler Pardun



2015-2020 VORTEX-SouthEast

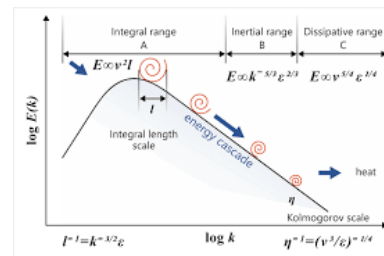
Cool season deployments of fixed facilities to North Alabama

Use these years of data to determine scales of motion and necessary observation spacing

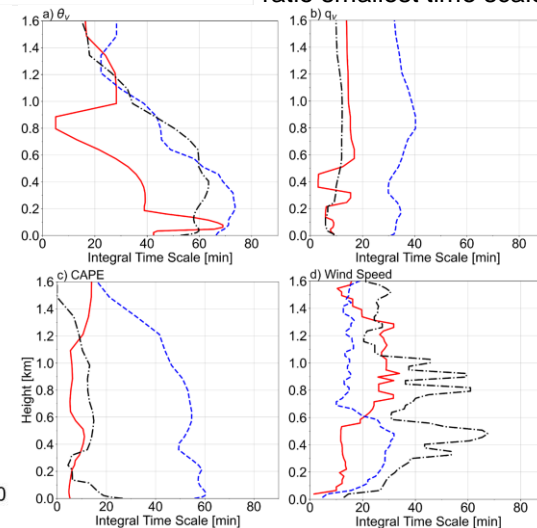
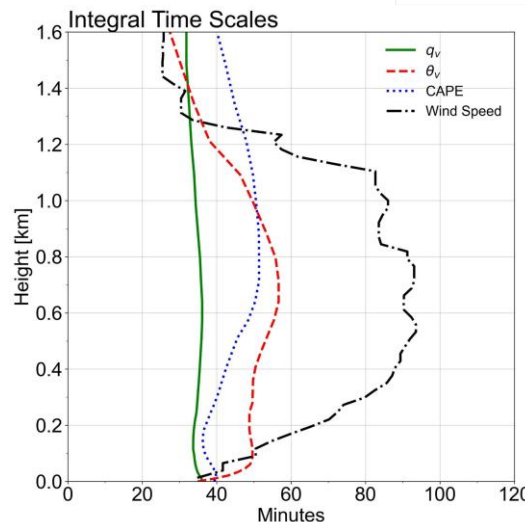
Time-to-space (Taylor's Frozen)

$$D = ITS \times U$$

D=distance, *ITS*= integral time scale,
U= mean wind speed



Note water vapor mixing ratio smallest time scale



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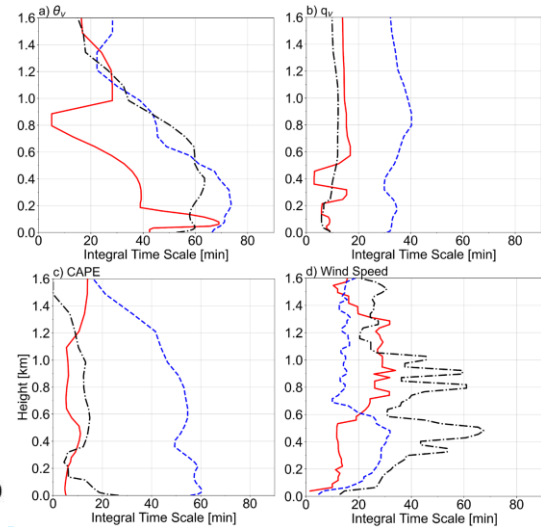
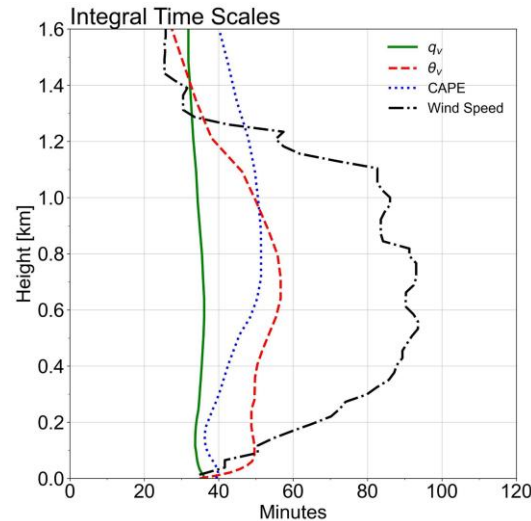
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Convective cases:

ITS ~ 40 min

$U \sim 15\text{-}20$ m/s

$D = 36 - 48$ km

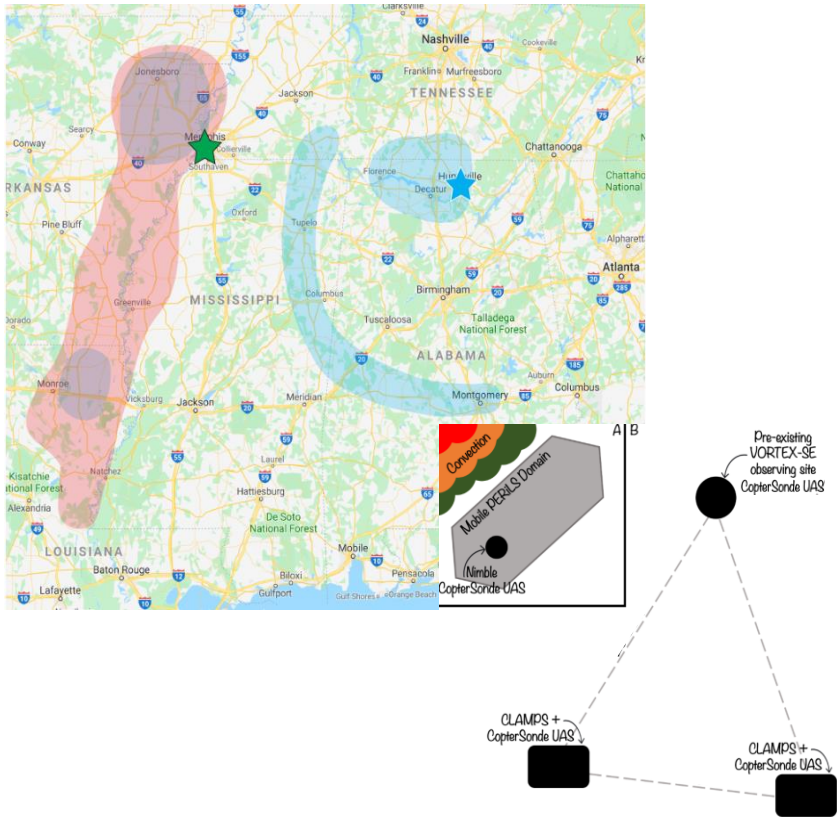




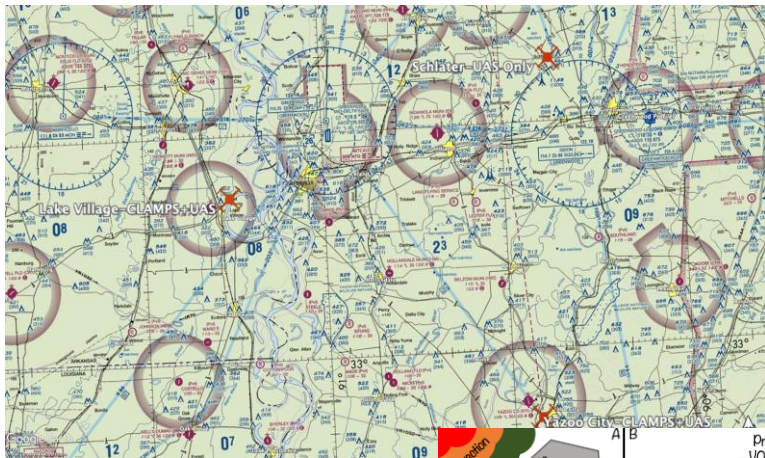
Innovation as motivation for PERiLS CONOPS

Need: *network* low-atmosphere observations in *challenging environment* of southeastern US

VORTEX-SE findings: above-surface variability critical



Innovation as motivation for PERiLS CONOPS



Need: *network* low-atmosphere observations in *challenging environment* of southeastern US

VORTEX-SE findings: above-surface variability critical, 2016-2019 remote sensor profiling obs suggested ~50 km min. spacing

PERiLS opportunity: deploy prototype network with *network-in-network* framework

- Network-in-network concept further enhanced by PERiLS mobile armada (esp. adaptable obs)
- Deploys only when high-impact weather is imminent

Iterations with NOAA UASD

- defined ultimate location of inner network
- led to elimination of nimble + fixed approach
- walk before you can run!

COA: 3 sites, 0–1.5km AGL

0–5000 feet AGL

